Poincaré inequalities revisited for dimension reduction

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Part I

Background and motivation

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A case study for global sensitivity analysis



A simplified flood model [looss, 2011], [looss and Lemaitre, 2015].

• 1 output: maximal annual overflow (in meters), denoted by S:

$$S = Z_v + H - H_d - C_b$$
 with $H = \left(\frac{Q}{BK_s\sqrt{\frac{Z_m-Z_v}{L}}}\right)^{0.6}$

where *H* is the maximal annual height of the river (in meters).

A case study for global sensitivity analysis

• 8 inputs variables assumed to be independent r.v., with distributions:

Input	Description	Unit	Probability distribution
$X_1 = Q$	Maximal annual flowrate	m ³ /s	Gumbel $G(1013, 558)$,
			truncated on [500, 3000]
$X_2 = K_s$	Strickler coefficient	-	Normal $\mathcal{N}(30, 8^2)$,
			truncated on $[15, +\infty[$
$X_3 = Z_v$	River downstream level	m	Triangular $\mathcal{T}(49, 50, 51)$
$X_4 = Z_m$	River upstream level	m	Triangular $\mathcal{T}(54, 55, 56)$
$X_5 = H_d$	Dyke height	m	Uniform $\mathcal{U}[7,9]$
$X_6 = C_b$	Bank level	m	Triangular $\mathcal{T}(55, 55.5, 56)$
$X_7 = L$	River stretch	m	Triangular $T(4990, 5000, 5010)$
$X_8 = B$	River width	m	Triangular $\mathcal{T}(295, 300, 305)$

• Aim: To detect unessential X_i 's, to quantify the influence of X_i 's on S, \ldots

A case study for global sensitivity analysis



Figure: The 3 distributions types of the case study, here with mean 0 and variance 1

Towards variance-based sensitivity measures

Framework. $X = (X_1, ..., X_d)$ is a vector of independent input variables with distribution $\mu_1 \otimes \cdots \otimes \mu_d$, and $g : \Delta \subseteq \mathbb{R}^d \to \mathbb{R}$ is such that $g(\mathbf{X}) \in L^2(\mu)$.

Sobol-Hoeffding decomposition [Sobol, 1993, Efron and Stein, 1981]

$$g(\mathbf{X}) = g_0 + \sum_{i=1}^d g_i(X_i) + \sum_{1 \le i < j \le d} g_{i,j}(X_i, X_j) + \dots + g_{1,\dots,d}(X_1, \dots, X_d)$$

The g_l 's satisfy $E[g_l(X_l)|X_J] = 0$ if $J \subsetneq I$, implying orthogonality. They are obtained sequentially via

$$\mathbb{E}(g(\mathbf{X})|\mathbf{X}_l) = \int_{\mathbb{R}^{d-|l|}} g(\mathbf{x}) d\mu_{-l}(\mathbf{x}_{-l})$$

Variance decomposition and Sobol indices

• Partial variances: $D_l = Var(g_l(X_l))$, and Sobol indices $S_l = D_l/D$

$$D := \operatorname{Var}(g(\mathbf{X})) = \sum_{I} D_{I}, \qquad 1 = \sum_{I} S_{I}$$

• Total index: $D_{i}^{\mathsf{T}} = \sum_{J \supseteq \{i\}} D_{J}, \qquad S_{i}^{\mathsf{T}} = \frac{D_{i}^{\mathsf{T}}}{D}.$

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dex: $D_{I}^{\mathsf{T}} = \sum_{I} z_{I} z_{I} \qquad S_{I}^{\mathsf{T}} = \frac{D_{I}^{\mathsf{T}}}{2}$

• Initial index.
$$D_i = \sum_{J \supseteq \{i\}} D_J, \qquad J_i = \overline{D}.$$

Derivative Global Sensitivity Measure (DGSM), [Sobol and Gershman, 1995], [Kucherenko et al., 2009]

$$\nu_i = \int \left(\frac{\partial g(\mathbf{x})}{\partial x_i}\right)^2 d\mu(\mathbf{x})$$

• Usage for screening.

If either $D_i^T = 0$ or $\nu_i = 0$, than X_i is non influential

Advantages / Drawbacks

	Computational cost	Interpretability
Sobol indices	-	+
DGSM	+	-

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Can we use DGSM to do screening based on Sobol indices?

Poincaré inequality (1-dimensional case)

A distribution μ satisfies a Poincaré inequality if the energy in $L^2(\mu)$ sense of any centered function is controlled by the energy of its derivative:

For all *h* in $L^2(\mu)$ such that $\int h(x)d\mu(x) = 0$, and $h'(x) \in L^2(\mu)$:

$$\int h(x)^2 d\mu(x) \leq C(\mu) \int h'(x)^2 d\mu(x)$$

The best constant is denoted $C_{\rm P}(\mu)$.

Link between total Sobol indices and DGSM

Theorem [Lamboni et al., 2013], extended in [Roustant et al., 2014]

If μ_i admits a Poincaré inequality, then there is a Poincaré-type inequality between total indices and DGSMs

 $D_i \leq D_i^{\mathrm{T}} \leq C(\mu_i) \nu_i$

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Proof. Denote $g_i^{\mathsf{T}}(\mathbf{x}) := \sum_{J \supset \{i\}} g_J(\mathbf{x}_J)$. Then:

$$\frac{\partial g(\mathbf{x})}{\partial x_i} = \frac{\partial g_i^{\mathsf{T}}(\mathbf{x})}{\partial x_i}$$

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$$egin{aligned} \mathcal{D}_i^\mathsf{T} &= \operatorname{Var}(m{g}_i^\mathsf{T}(\mathbf{x})) &= & \int ig(m{g}_i^\mathsf{T}(\mathbf{x})ig)^2 \, m{d} \mu(\mathbf{x}) \ && \leq & \mathcal{C}(\mu_i) \int ig(rac{\partial m{g}^\mathsf{T}(\mathbf{x})}{\partial m{x}_i}ig)^2 \, m{d} \mu(\mathbf{x}) = \mathcal{C}(\mu_i)
u_i \end{aligned}$$



Figure: Total Sobol index S_i^T & Upper bound $C(\mu_i)\nu_i/D$

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- When is the upper bound $C(\mu_i)\nu_i$ large (compared to D_i^T)?

- Even if the Poincaré inequality is not accurate, *it may be enough to screen out the less influential variables* → Z_m, L, B in the case-study
- When is the upper bound C(µ_i)ν_i large (compared to D^T_i)?



Why not transforming the problem to get uniform distributions?

Example with X_1, X_2 i.i.d. $\mathcal{N}(0, 1)$ truncated on I = [-b, b]



The Sobol indices of f and g are the same

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Difference on optimal upper bounds computed with DGSM

$\mu(I)$	ST	Upper bound with DGSM	Upper bound with DGSM	
		Original problem (with f)	Transformed problem (with g)	
1	0.5	0.5	$+\infty$	
0.95	0.5	0.52	1.48	
0.75	0.5	0.56	1.00	

The derivatives are larger on the transformed problem \Rightarrow larger bounds

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1D Poincaré constants: Known results

pdf	Support	$C_{P}(\mu)$	$f_{\rm opt}(\mathbf{x})$
Uniform	[a, b]	$(b-a)^2/\pi^2$	$\cos\left(\frac{\pi(x-a)}{b-a}\right)$
$\mathcal{N}(m, s^2)$	R	<i>s</i> ²	x - m
	$[r_{n,i}, r_{n,i+1}]$ (*)	1/(<i>n</i> +1)	$H_{n+1}(x)$
Double exp. $e^{- x }dx/2$	R	4	×
Logistic $\frac{e^x}{(1+e^x)^2}dx$	R	4	×

(*) H_n is the Hermite polynomial of degree n, and $r_{n,1}, \ldots, r_{n,n}$ its zeros.

Sobol indices and DGSM are linked by Poincaré-type inequalities

$$D_i^{\mathsf{T}} \leq C(\mu_i)
u_i \qquad D_{i,j}^{\mathsf{super}} \leq C(\mu_i) C(\mu_j)
u_{i,j}$$

- OGSM are easier to compute but Sobol indices are more interpretable ⇒ DGSM may allow doing low-cost screening based on Sobol indices
- The aim: To look for the exact Poincaré constants for distributions met in practice:
 - Frequently: Uniform (truncated) Gaussian Triangular (truncated) lognormal – Exponential – (truncated) Weibull – (truncated) Gumbel
 - Less frequently: (Inverse) Gamma Beta Trapezoidal Generalized Extreme Value

- Theory for optimal inequalities
- Semi-analytical results
- A numerical method
- Applications

Part II

Theory for optimal inequalities

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Mathematical setting

Definitions and assumptions

- Ω : an open interval (a, b) of \mathbb{R} (possibly unbounded)
- μ(dt) = ρ(t)dt: A continuous measure supported by Ω.
 ρ > 0 on Ω, continuous on Ω and piecewise C¹ on Ω.
- f': weak derivative of f, i.e. s.t. for all ϕ of class C^{∞} with compact support

$$\int_{\Omega} f(t)\phi'(t)dt = -\int_{\Omega} f'(t)\phi(t)dt.$$

• Sobolev spaces • $\mathcal{H}^1_{\mu}(\Omega) = \{f \in L^2(\mu) \text{ such that } f' \in L^2(\mu)\}$ • $\mathcal{H}^{\ell}_{\mu}(\Omega) = \{f \in L^2(\mu) \text{ such that for all } k \leq \ell, f^{(k)} \in L^2(\mu)\}$

When weighted Sobolev spaces collapse to usual Sobolev spaces

Assume that μ is a bounded perturbation of $\mathcal{U}(\Omega)$, i.e. $0 < m < \rho(t) < M$. Then:

$$L^{2}(\mu) = L^{2}(\mathcal{U}(\Omega)) \qquad \mathcal{H}^{\ell}_{\mu}(\Omega) = \mathcal{H}^{\ell}_{\mathcal{U}(\Omega)}(\Omega)$$

with equivalent norms.

Poincaré inequality and Rayleigh ratio

Rayleigh ratio For $f \in \mathcal{H}^1_\mu(\Omega)$: $J(f) = \frac{\int_\Omega f'^2 d\mu}{\int_\Omega f^2 d\mu} = \frac{\|f'\|^2}{\|f\|^2}$

Finding the Poincaré constant is equivalent to:

$$\min_{f\in\mathcal{H}^{1}_{\mu}(\Omega)}J(f)\quad s.t.\quad \int_{\Omega}f\,d\mu=0$$

and $C_{\rm P}(\mu)$ denotes the *inverse* of the minimum.

Optimizing a Rayleigh ratio in finite dimensions

Exercice!

Let *A* a positive definite matrix on \mathbb{R}^n . Find:



with $||x||_{A}^{2} = x^{T}Ax$

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Let *A* a positive definite matrix on \mathbb{R}^n . Find:

 $\min_{x\in\mathbb{R}^n}\frac{\|x\|_A^2}{\|x\|^2}$

with $||x||_{A}^{2} = x^{T}Ax$

Solution. A is diagonalisable in an orthonormal basis u_k :

 $Au_k = \lambda_k u_k$

with $\lambda_1 \ge \cdots \ge \lambda_n > 0$. Expand *x* in the basis: $x = \sum x_k u_k$, then $Ax = \sum \lambda_k x_k u_k$:

$$\frac{\|\boldsymbol{x}\|_{\boldsymbol{A}}^2}{\|\boldsymbol{x}\|^2} = \frac{\sum \lambda_k \boldsymbol{x}_k^2}{\sum \boldsymbol{x}_k^2} \ge \lambda_1$$

with equality if $x = u_1$.

Theorem (Synthesis from [Bobkov and Götze, 2009] and [Dautray and Lions, 1990])

Assume that $\Omega = (a, b)$ is bounded, and that $\rho(t) = e^{-V(t)} > 0$ on $\overline{\Omega} = [a, b]$. A minimizer *f* of the Rayleigh ratio is obtained by solving

 $Lf := f'' - V'f' = -\lambda f$ with f'(a) = f'(b) = 0

when $\lambda =: \lambda(\mu)$ is the smallest possible value, called spectral gap. Furthermore, $\lambda(\mu)$ is a simple eigenvalue and *f* is strictly monotone.

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Ideas for the proof. Show the connections between the three problems P1 Find $f \in \mathcal{H}^{1}_{\mu}(\Omega)$ s.t. $J(f) = \frac{\|f'\|^{2}}{\|f\|^{2}}$ is minimum under $\int fd\mu = 0$ P2 Find $f \in \mathcal{H}^{1}_{\mu}(\Omega)$ s.t. $\langle f', g' \rangle = \lambda \langle f, g \rangle \quad \forall g \in \mathcal{H}^{1}_{\mu}(\Omega)$ P3 Find $f \in \mathcal{H}^{2}_{\mu}(\Omega)$ s.t. $f'' - V'f' = -\lambda f$ and f'(a) = f'(b) = 0

(P1) \iff (P2) (for the smallest positive λ). Start from (P2):

$$\langle f', oldsymbol{g}'
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Up to a switch in order to make coercive the left side, we can 'diagonalize': there exists a Hilbert basis $(u_k)_{k\geq 0}$ and an increasing sequence $(\lambda_k)_{k\geq 0}$ of positive numbers that tends to infinity such that:

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Remark that:

- $\lambda_k = 0 \iff k = 0$, and $u_0 = 1$
- $\int f d\mu = 0 \iff \langle f, 1 \rangle = 0$

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Thus *f* is written: $f = \sum_{k \ge 1} f_k u_k$. Finally,

$$J(f) = \frac{\|f'\|^2}{\|f\|^2} = \frac{\sum_{k=1}^{+\infty} \lambda_k f_k^2}{\sum_{k=1}^{+\infty} f_k^2} \ge \lambda_1 > 0$$

with equality iff $f \in \mathbb{R}$ u_1 .

 $(P2) \iff (P3)$ Formally the link comes from an integration by part (IPP):

$$\langle f',g'\rangle = \int_a^b f'g'\rho = [(f'\rho)g]_a^b - \int_a^b (f'\rho)'g$$
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Thus the two are equal for all $g \in \mathcal{H}^1_\mu(\Omega)$ iff:

This proves $(P2) \leftarrow (P3)$, since *f* is regular enough (IPP is valid). Conversely, an argument of regularity is necessary. One can show that if *f* is solution of (P2), then $(f'\rho)$ is of class C^1 , and more precisely:

$$f'(x) = \frac{\lambda}{\rho(x)} \int_x^b f(t)\rho(t)dt.$$

Neumann and Dirichlet spectral gaps

If f is enough derivable, finding $f \uparrow of$ the Neumann spectral problem

$$Lf := f'' - V'f' = -\lambda f, \qquad f'(a) = f'(b) = 0$$

is equivalent to finding g > 0 of the *Dirichlet* spectral problem

$$Kg := g'' - V'g' - V''g = -\lambda g, \qquad g(a) = g(b) = 0$$

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Main idea. Consider g = f'

Monotonicity with respect to the interval

$$I \subseteq J \quad \Rightarrow \quad C_{\mathrm{P}}(\mu_{|I}) \leq C_{\mathrm{P}}(\mu_{|J})$$

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$$I_{\epsilon}\uparrow I \quad \Rightarrow \quad C_{\mathrm{P}}(\mu_{|I_{\epsilon}})
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$$I_{\epsilon}\uparrow I \quad \Rightarrow \quad C_{\mathrm{P}}(\mu_{|I_{\epsilon}}) o C_{\mathrm{P}}(\mu_{|I})$$

Consequence.

We can assume that $\Omega = (a, b)$ is bounded and that ρ does not vanish on $\overline{\Omega}$.

Sketch of proof for monotonicity.

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$$\operatorname{Var}_{\mu_{|l}}(f) = \inf_{a} \int_{l} (f-a)^{2} \frac{d\mu}{\mu(l)}$$

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$$\begin{aligned} \operatorname{Var}_{\mu_{|I}}(f) &= \inf_{a} \int_{I} (f-a)^{2} \frac{d\mu}{\mu(I)} \\ &\leq \inf_{a} \int_{J} (\tilde{f}-a)^{2} \frac{d\mu}{\mu(I)} \end{aligned}$$

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Sketch of proof for monotonicity.

For $f \in \mathcal{H}^1(\mu_{|I})$, extend it on *J* with a constant outside *I*. This is \tilde{f} .

$$\begin{aligned} \operatorname{Var}_{\mu_{|I}}(f) &= \inf_{a} \int_{I} (f-a)^{2} \frac{d\mu}{\mu(I)} \\ &\leq \inf_{a} \int_{J} (\tilde{f}-a)^{2} \frac{d\mu}{\mu(I)} \leq C_{\mathrm{P}}(\mu) \int_{J} (\tilde{f}')^{2} \frac{d\mu}{\mu(I)} = C_{\mathrm{P}}(\mu) \int_{I} (f')^{2} d\mu_{|I}. \end{aligned}$$

Sketch of proof for continuity.

- From monotonicity, $C_{\mathrm{P}}(\mu_{|I_{\epsilon}}) \leq C_{\mathrm{P}}(\mu_{|I})$
- Then, choose $f \in \mathcal{H}^1(\mu_{|I})$, and check with Lebesgue theorem that:

$$\frac{\mathrm{Var}_{\mu_{|I}}(f)}{\int_{\Omega} f'^2 \mathcal{d}_{\mu_{|I}}} = \lim_{\epsilon \to 0} \frac{\mathrm{Var}_{\mu_{|I_{\epsilon}}}(f)}{\int_{I_{\epsilon}} f'^2 \mathcal{d}_{\mu_{|I_{\epsilon}}}} \leq \lim_{\epsilon \to 0} \mathcal{C}_{\mathrm{P}}(\mu_{|I_{\epsilon}})$$

Properties for symmetric measures on symmetric intervals

Let I = (-a, a) be a symmetric interval, and μ an even measure on \mathbb{R} .

Improved result for monotonicity

 $C_{\mathrm{P}}(\mu_{|I}) \leq \mu(I)^2 C_{\mathrm{P}}(\mu)$

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Improved result for monotonicity

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Symmetry and odd functions

The infemum of the Rayleigh ratio on I can be found among odd functions

Part III

Semi-analytical results

An example: The truncated normal distribution

Poincaré constant of the truncated Normal distribution

Define:

$$h_0(\lambda,t) = M_{\frac{1-\lambda}{2};\frac{1}{2}}\left(\frac{t^2}{2}\right) \qquad h_1(\lambda,t) = M_{\frac{2-\lambda}{2};\frac{3}{2}}\left(\frac{t^2}{2}\right)$$

where the so-called *Kummer's function* $M_{a_1,b_1}(z) = {}_1F_1(a_1;b_1;z)$ is an example of *hypergeometric series* $\sum_{p\geq 0} x_p$ satisfying

$$\frac{x_{\rho+1}}{x_{\rho}} = \frac{(\rho+a_1)z}{(\rho+b_1)(\rho+1)}, \qquad x_0 = 1$$

Notice that h_0 and h_1 generalize Hermite polynomials: When λ is an odd (resp. even) positive integer, then $t \mapsto h_0(\lambda, t)$ (resp. $t \mapsto t.h_1(\lambda, t)$) is proportional to the Hermite polynomial of degree $\lambda - 1$. Then the spectral gap of $\mathcal{N}(0, 1)_{|[a,b]}$ is the first zero of the function

$$d(.) = bh_0(., a)h_1(., b) - ah_0(., b)h_1(., a)$$

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• Look for a series expansion $g(t) = \sum_{n \ge 0} c_n t^n \Rightarrow c_{n+2} = \frac{n-(\lambda-1)}{(n+1)(n+2)}c_n$.

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• Look for a series expansion $g(t) = \sum_{n \ge 0} c_n t^n \Rightarrow c_{n+2} = \frac{n - (\lambda - 1)}{(n+1)(n+2)} c_n$. Split g into even an odd part, $g(t) = g_0(t) + t.g_1(t)$. Then:

$$g(t) = c_0 h_0(\lambda, t) + c_1 t h_1(\lambda, t)$$

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• Look for a series expansion $g(t) = \sum_{n \ge 0} c_n t^n \Rightarrow c_{n+2} = \frac{n - (\lambda - 1)}{(n+1)(n+2)} c_n$. Split g into even an odd part, $g(t) = g_0(t) + t.g_1(t)$. Then:

$$g(t) = c_0 h_0(\lambda, t) + c_1 t h_1(\lambda, t)$$

• Now, g(a) = g(b) = 0 lead to the linear system Xc = 0, with:

$$X = \begin{pmatrix} h_0(\lambda, a) & ah_1(\lambda, a) \\ h_0(\lambda, b) & bh_1(\lambda, b) \end{pmatrix} \qquad c = \begin{pmatrix} c_0 \\ c_1 \end{pmatrix}$$

$$g'' - t g' = -(\lambda - 1)g,$$
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This system must be singular, otherwise *g* would be identically zero. Thus det(X) = 0, leading to $d(\lambda) = 0$.

Truncated normal distribution – Symmetric case: I = [-b,b]



Figure: Poincaré constant of $\mu = \mathcal{N}(0, 1)$ truncated on I = [-b, b], vs $\mu(I)$

 σ_I^2 : variance of the truncated normal on *I* – Black points: Hermite polynomials of even degree.

Semi-analytical results

Truncated normal distribution – General case



Figure: Poincaré constant of $\mathcal{N}(0, 1)$ truncated on I = [a, b].

Colored points: Hermite polynomials (up to degree 100).

Summary: General methodology for finding optimal constants on [a, b]

- Consider the spectral problem $f'' V'f' = -\lambda f$ f'(a) = f'(b) = 0
- 3 Find a basis of 2 independent solutions $f_{1,\lambda}(t), f_{2,\lambda}(t)$
- The Neumann conditions lead to a singular linear system

$$\begin{pmatrix} f'_{1,\lambda}(a) & f'_{2,\lambda}(a) \\ f'_{1,\lambda}(b) & f'_{2,\lambda}(b) \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

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Variants.

- Dirichlet problem (ex: Truncated Gaussian)
- Symmetry (ex: Triangular)

1D Poincaré constants: Additional results

pdf	Support	Copt	Form of f _{opt} (x)
Uniform	[<i>a</i> , <i>b</i>]	$(b-a)^2/\pi^2$	$\cos\left(\frac{\pi(x-a)}{b-a}\right)$
$\mathcal{N}(\mu, \sigma^2)$	R	σ^2	$X - \mu$
	$[r_{n,i}, r_{n,i+1}]$	1/(<i>n</i> +1)	$H_{n+1}(x)$
	[<i>a</i> , <i>b</i>]	see before	related to Kummer
Db. exp. $e^{- x }dx/2$	R	4	×
(*)	[<i>a</i> , <i>b</i>], <i>ab</i> > 0	$\left(\frac{1}{4}+\omega^2\right)^{-1}$	$e^{x/2}\cos(\omega x + \phi)$
(*, **)	[<i>a</i> , <i>b</i>], <i>ab</i> ≤ 0	$> \left(\frac{1}{4} + \omega^2\right)^{-1}$	$e^{ x /2} imes$ trig. spline
Logistic $\frac{e^x}{(1+e^x)^2}dx$	R	4	×
Triangular	[-1,1]	≈ 0.1729	linked to Bessel J ₀

(*) For the truncated Exponential on $[a, b] \subseteq \mathbb{R}^+$, we use $\omega = \pi/(b-a)$ (**) If a < 0 < b, the spectral gap is the zero in $]0, \min(\pi/|a|, \pi/|b|)[$ of $x \mapsto \operatorname{cotan}(|a|x) + \operatorname{cotan}(|b|x) + 1/x$

Part IV

A numerical method



Figure: Basis of finite elements \mathbb{P}_1 on [0, 1]. The g_i 's are hat functions for i = 1, ..., n - 1, truncated at the boundaries (i = 0 and i = n).

The idea is to solve numerically the spectral problem (P2)

$$\langle f', g'
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 $K_h \mathbf{f_h} = \lambda M_h \mathbf{f_h}$

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Using the Choleski dec. of $M_h = L_h L_h^T$, we obtain an eigenvalues problem

 $\widetilde{K_h}\widetilde{\mathbf{f}_h} = \lambda \widetilde{\mathbf{f}_h}$

with
$$\widetilde{K_h} = L_h^{-1} K_h (L_h^T)^{-1}$$
 and $\widetilde{f_h} = L_h^T f_h$.

Convergence properties

Proposition

Assume that Ω is bounded and $\rho > 0$ on $\overline{\Omega}$. Consider the solutions of the spectral problem in \mathbb{P}_1 ,

 $\mathbf{0} = \lambda_{\mathbf{0},h} \leq \lambda_{\mathbf{1},h} \leq \cdots \leq \lambda_{n,h}$

and $u_{0,h}, u_{1,h}, \ldots, u_{n,h}$. corr. eigenvectors. Let $\ell \geq 1$ s.t. $f_{opt} \in \mathcal{H}_{\mu}^{\ell+1}(\Omega)$. Then:

 $|\lambda_{1,h} - \lambda(\mu)| = O(h^{2\ell}), \qquad |u_{1,h} - f_{opt}| = O(h^{\ell})$

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Proof. If $\mu = \mathcal{U}(\Omega)$, the result comes from theory on finite elements (see e.g. [Raviart and Thomas, 1988]), as all eigenvalues are simple. This also applies under the assumptions above since μ is a bounded perturbation of $\mathcal{U}(\Omega)$: $0 < m < \rho(t) < M$.
Part V

Applications

Come-back to the case study



Come-back to the case study



Application on a 1D hydraulic model



- Mascaret simulator on Vienne river (Saint Venant Lab.)
- d = 37 random inputs (uniform and truncated Gaussian)
- Output: The water level at a specific river location
- Adjoint model gives derivatives (cost independent of *d*) and DGSM [Petit et al., 2016]

Application on a 1D hydraulic model

Study with n = 20,000 on 5 inputs previously identified as active

Inputs	$K_{s,c}^{11}$	$K_{s,c}^{12}$	dZ^{11}	dZ^{12}	Q
μ	Û	Û	$\mathcal{T}N$	$\mathcal{T}N$	$\mathcal{T}N$
S^{T}	0.456	0.0159	0.293	0.015	0.239
	(2 <i>e</i> –3)	(1 <i>e</i> -4)	(1 <i>e</i> –3)	(1 <i>e</i> -4)	(1 <i>e</i> –3)
By double exponential transport					
Upper bound	-	-	1.844	0.116	1.504
	-	-	(2 <i>e</i> –3)	(2 <i>e</i> –3)	(1.5 <i>e</i> –2)
By logistic transport					
Upper bound	-	-	0.461	0.028	0.376
	-	-	(4 <i>e</i> -3)	(5 <i>e</i> -4)	(4 <i>e</i> -3)
Optimal Poincaré constant					
Optimal bound	0.625	0.029	0.288	0.017	0.235
	(2 <i>e</i> -4)	(1 <i>e</i> –5)	(3 <i>e</i> -3)	(3 <i>e</i> -4)	(2 <i>e</i> -3)

Part VI

Conclusion

Conclusions

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● DGSM allow doing low-cost screening based on Sobol indices ⇒ Will work if the function is not varying too quickly

- DGSM allow doing low-cost screening based on Sobol indices ⇒ Will work if the function is not varying too quickly
- C_P(μ) can be computed semi-analytically for simple distributions, e.g. *in blue* in our initial list:
 - Frequently: Uniform (truncated) Gaussian Triangular (truncated) lognormal – truncated Exp. – (truncated) Weibull – (truncated) Gumbel
 - Less frequently: (Inverse) Gamma Beta Trapezoidal Generalized Extreme Value
- $C_{\rm P}(\mu)$ can be computed numerically with finite elements.

See more details on our preprint

https://hal.archives-ouvertes.fr/hal-01388758

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Part VII

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